

# Composing Moves: How Procedural Memory Builds Novel Action

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# CONTENTS

- 01** | Why Compositionality?
- 02** | Three Desiderata
- 03** | Architectural Sketch
- 04** | Compositionality in Action
- 05** | Normative Profile

01

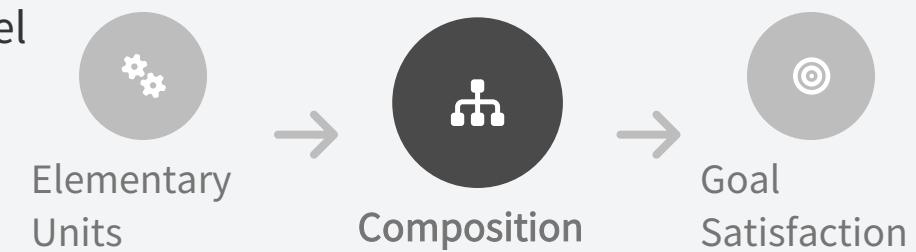
Why Compositionality?



# The Serial-Order Problem

Lashley's challenge to stimulus-response chaining

Stimulus-response chaining fails to explain the flexible sequencing of novel skilled acts. The motor system must compose elementary units into hierarchically ordered, context-sensitive sequences that satisfy a distal goal.





# From Novel Gestures to Tools

Apraxia data reveals a specific deficit in composing unfamiliar kinematic chunks into a coherent plan. Patients can grasp objects but fail to assemble multi-step tool-use actions or imitate meaningless gestures, pointing to a failure of compositional reasoning, not low-level execution.

## Intact Execution

Basic grasping and simple movements are preserved.



## Compositional Failure

Cannot assemble sub-actions for novel tool use.



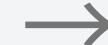
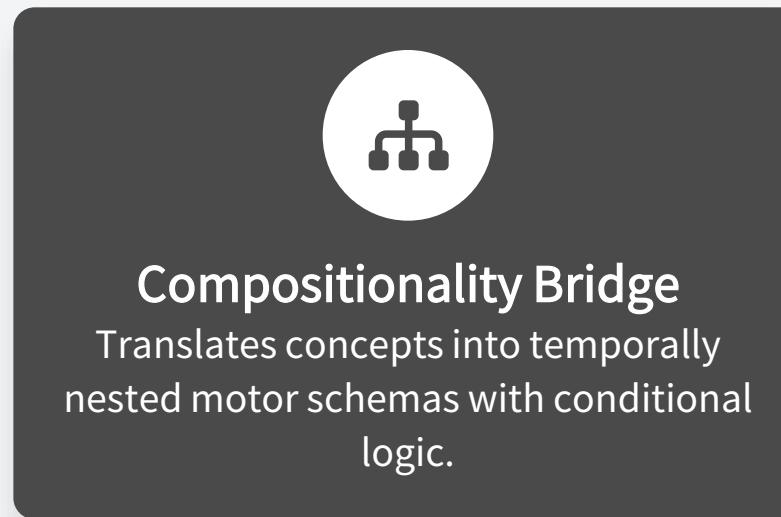


# The Declarative–Procedural Interface

How sparse symbols guide complex action.



**Verbal Instruction**  
"Flip the omelette"



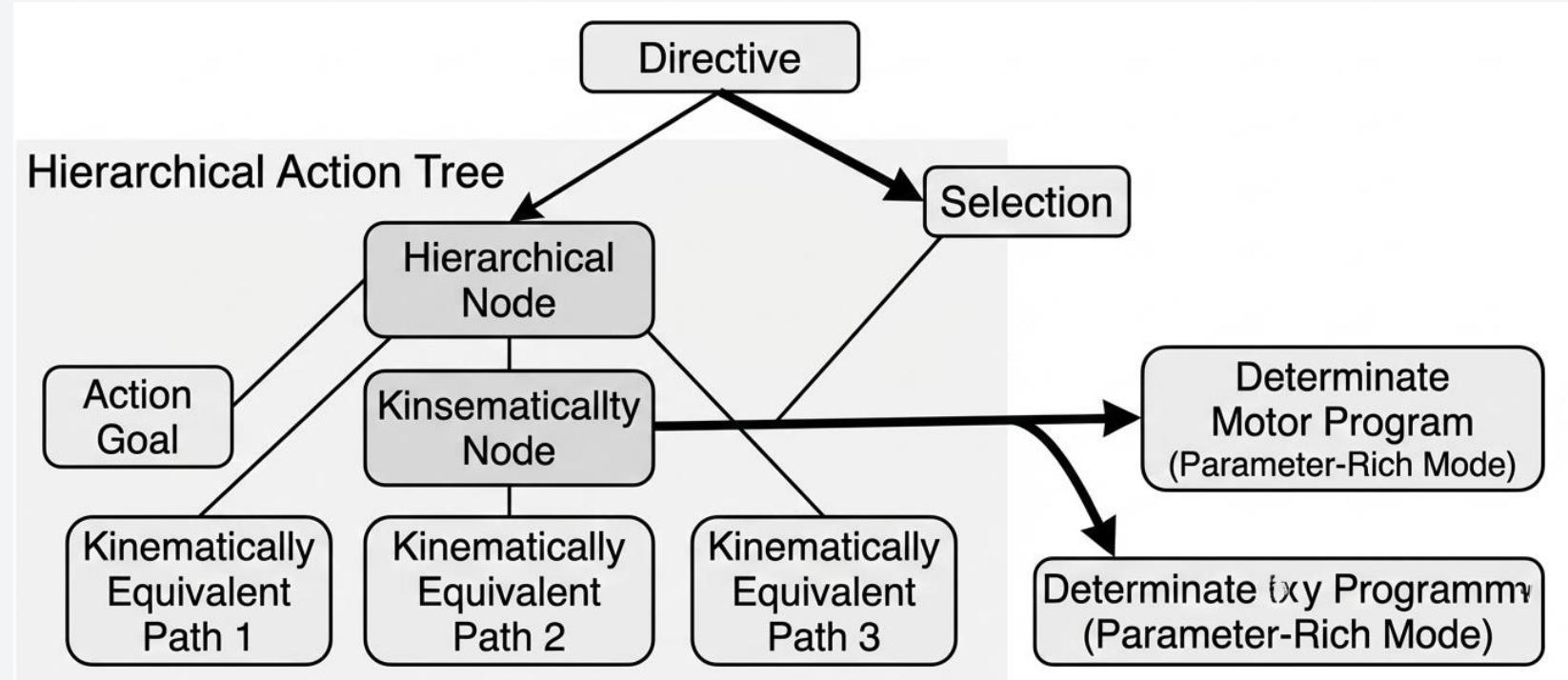
**Motor Execution**  
Coordinated Action



# 02 Three Desiderata

# Method-Specific Directivity

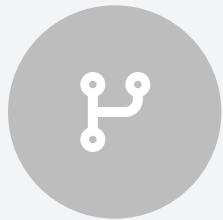
A directive must pick out one determinate motor program among kinematically equivalent paths.





# Sequencing & Branching

Real skills demand conditional logic and parallel coordination.



## Conditional Branching

Encoding "if-then" transitions based on context.



## Parallel Synergies

Coordinating multiple effectors simultaneously.



## Nested Timing

Tracking sub-goal completion to gate the next chunk.

Only compositional representations can encode this level of complexity.





# Error Evaluation: Two Types of Failure



## Execution Noise

The appropriate action is performed, but with spatial or temporal flaws (e.g., tremor, weakness). The **content** is correct, but the **precision** is lacking.



## Content Mismatch

A well-formed but inappropriate action is produced (e.g., brushing teeth vs. circular motion). The **content** itself is wrong, a true **misrepresentation**.

Compositional structure supplies the **internal standards** needed to distinguish these errors.



# 03 Architectural Sketch



# Hybrid Practical Concepts

Drawing on Pavese, primitive action concepts combine descriptive object-properties with directive force. Their Fregean modes of presentation are recombined by productive reasoning to assemble novel yet determinate motor plans.

  
**Descriptive**  
(Object Properties)

+

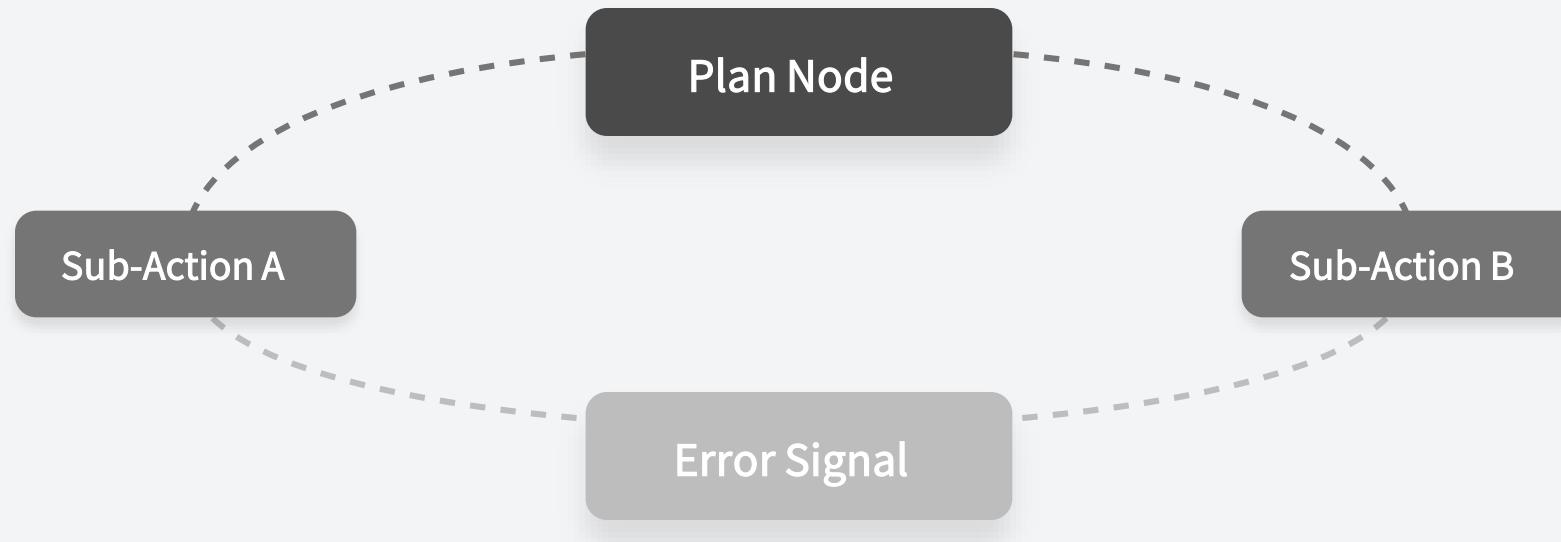
  
**Directive**  
(Force / Goal)



  
**Hybrid Concept**  
(Graspable-as-Cup)



# Hierarchical Forward Models



Each node pairs an efference copy with a predicted sensory effect. Mismatches propagate upward, supplying **fine-grained error signals** that target the offending constituent.



# 04 Compositionality in Action



# Case Study: The Novel Tool Test



## Familiar Object

Stored motor program: "Stab/Pierce"



## New Context

Requires novel action: "Scoop"



## Apraxic Failure

Cannot re-compose sub-actions.

Successful agents compose "scoop" kinematics with container affordance; apraxics cannot re-compose stored sub-actions under new functional goals.





## Meaningless Gesture Imitation

Copying an arbitrary hand-configuration requires parsing the demonstration into joint-angle constituents, reordering them, and aligning with one's own body schema. This offline assembly is enabled by compositional representation.

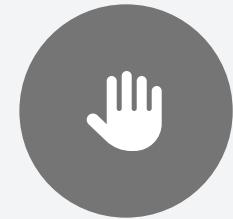
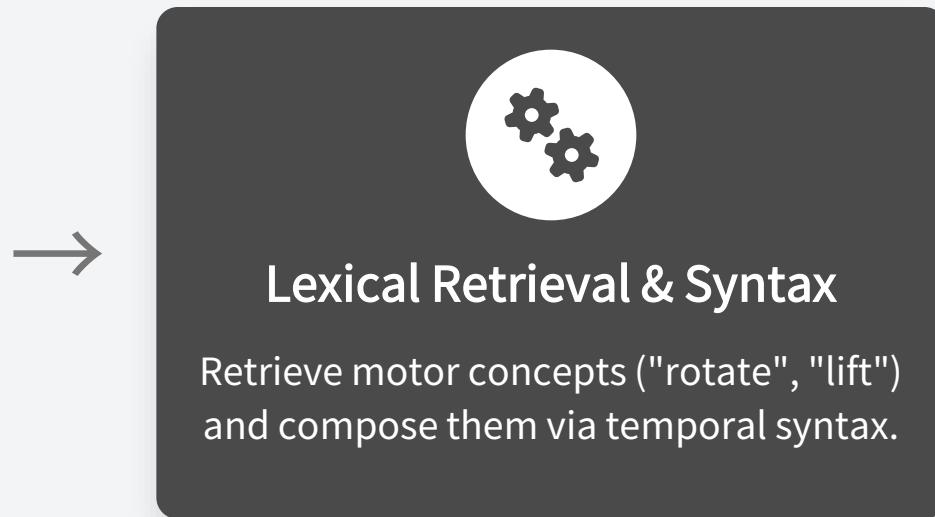




# Language-Driven Composition



**Linguistic Input**  
"Rotate 90° clockwise then lift"



**Motor Plan**  
Composed Action

The same combinatorial engine underlies both invented and routine acts.



# 05 Normative Profile



### External Goal (Success)

Did the action achieve the desired outcome in the world? This is a matter of **success**.



### Internal Goal (Correctness)

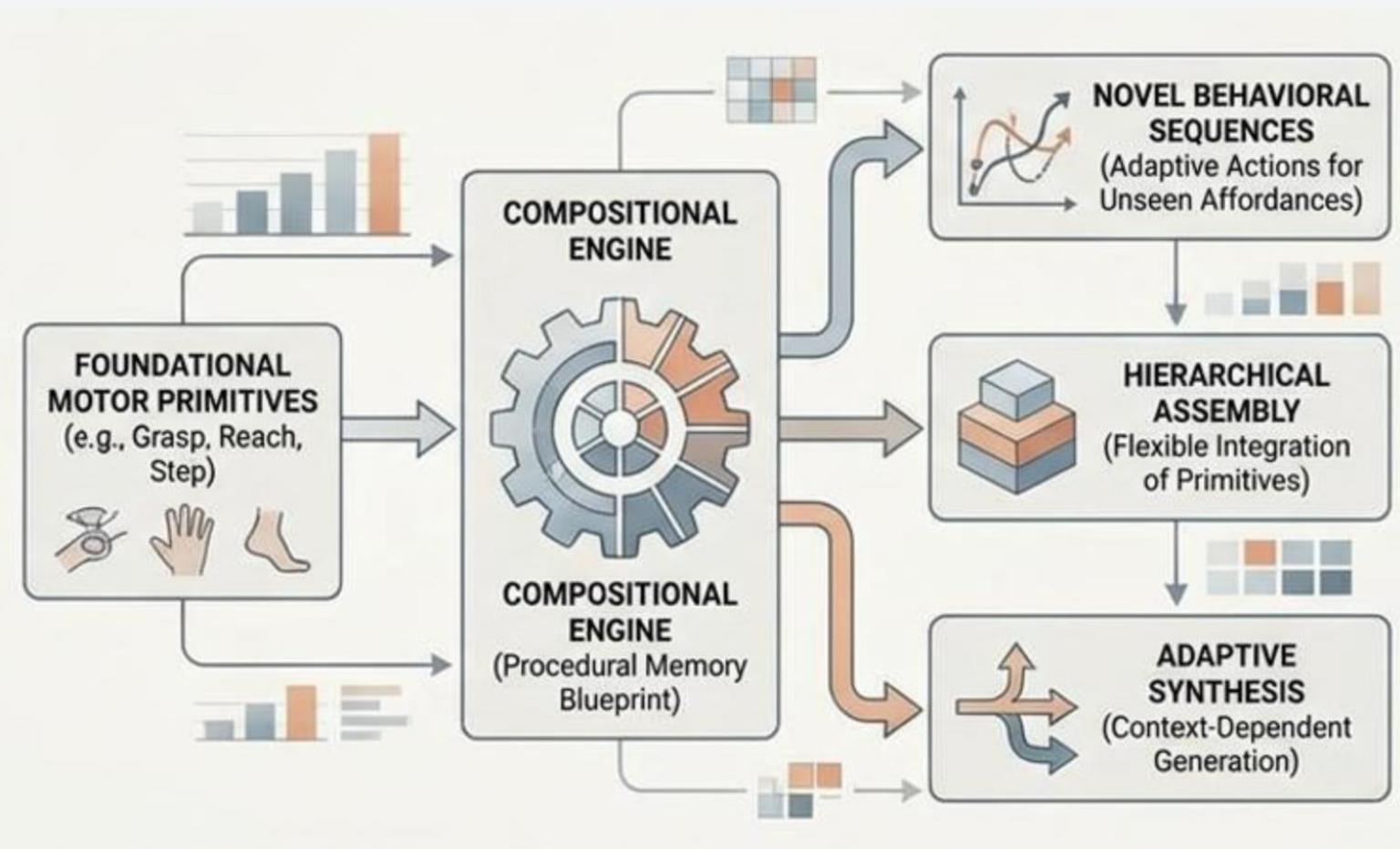
Did the action conform to its learned internal standard? This is a matter of **correctness**.

An action can be a "success" but still be "incorrect" (false procedural memory). Only a **content-based account** can distinguish them.



# Context Without Explosion

Compositional schemes avoid encoding infinite context-action pairs. Variables are bound online during execution, letting finite schemas generate context-appropriate muscle patterns while keeping satisfaction conditions intact.





# Rationality Preservation



## Expert Error

A proficient agent makes a mistake.



## Misrepresentation

Fault is located in a mis-composed constituent.



## Preserved Rationality

Global rationality and agency are shielded.

This explains **graded responsibility** and distinguishes skill error from agentive failure.



# 06 Anti-Rep Challenges

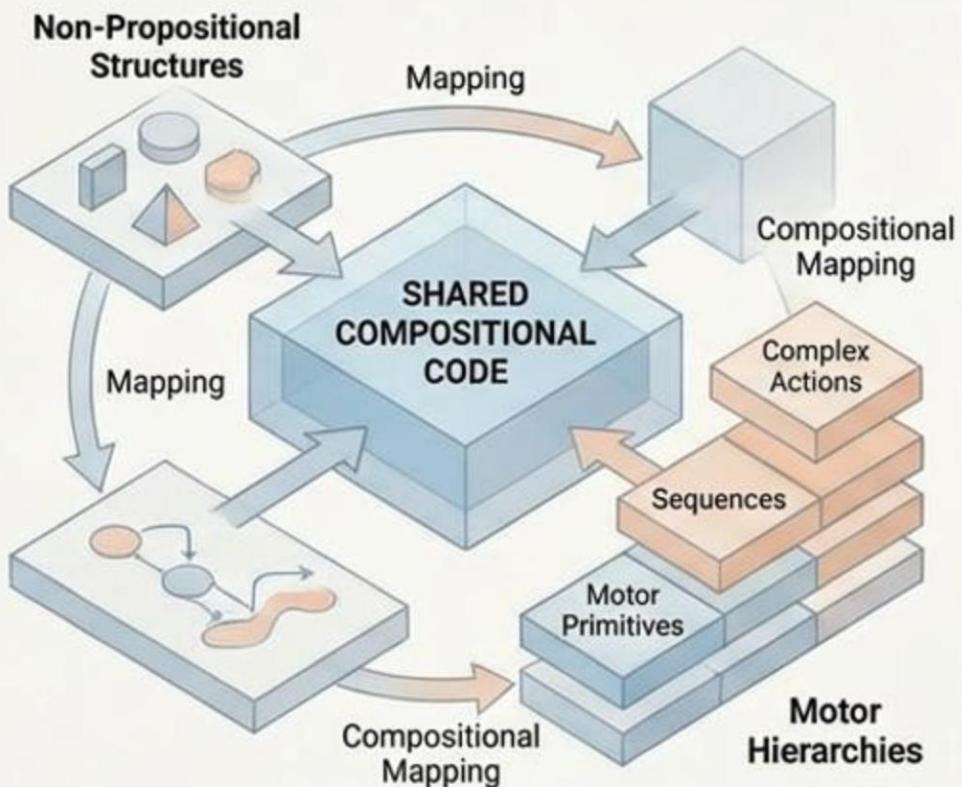
## The Enactivist Challenge

- Radical enactivism denies symbolic-to-motor translation.
- Pre-linguistic infants compose novel actions without symbols.



## The Paradox

## The Compositional Framework



## Evidenced Solution

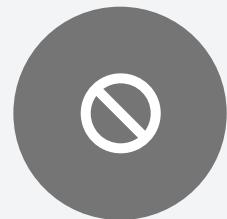
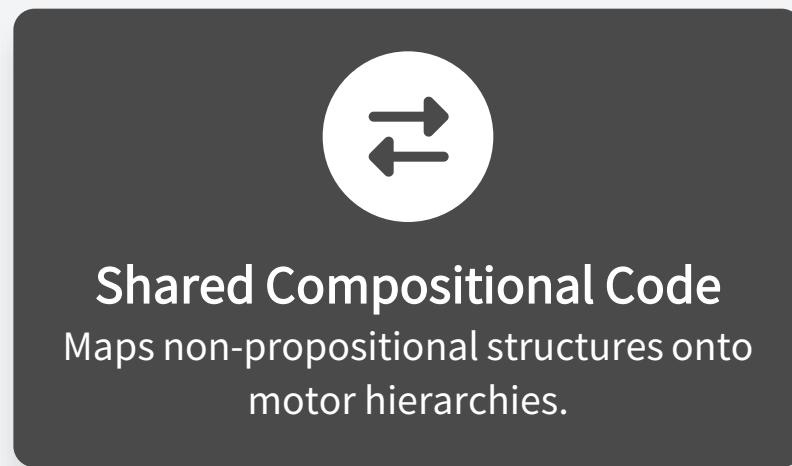
- Only evidenced solution: Shared Compositional Code.
- Maps non-propositional structures onto motor hierarchies.
- Explains generation of novel behavioral sequences.



# Challenge: Interface Without Translation



**Pre-linguistic Infant**  
Composes novel actions.



**Radical Enactivism**  
Denies symbolic-to-motor  
translation.

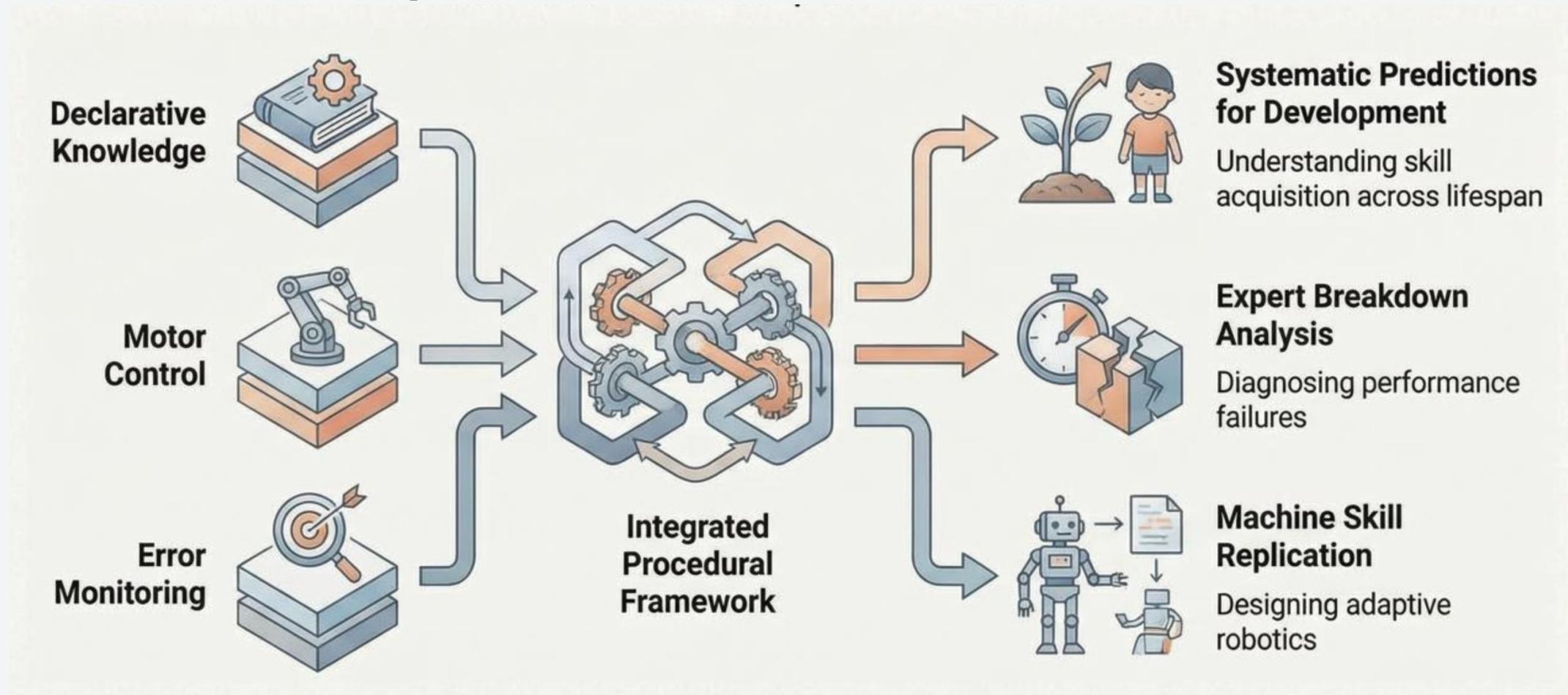
The only evidenced solution is a **shared compositional code**.



# 07 Upshot & Outlook



# Upshot: A Unified Explanation





# Upshot: AI Ramifications

- Agentic systems, to be useful, must act, and their plans are obviously compositional. To make them more robust, we should understand that they need equally informative success / failure signals to adapt to their situation.



THANK  
YOU

